

# Quantum Field Theory

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# Chapter 1 Introduction

## Necessity of field theory in relativistic system

Schrodinger equation  $\Rightarrow$  conservation of particle number.

$$H\psi = i\hbar \frac{\partial \psi}{\partial t} \quad \Rightarrow \quad \frac{d}{dt} \int d^3x \psi^\dagger \psi = 0 \rightarrow \int d^3x (\psi^\dagger \psi) \quad \text{indep of time}$$

If  $H$  is hermitian,  $H = H^\dagger$ . Then number of particles is conserved and no particle creation or annihilation.

Canonical commutation relation gives uncertainty relation,

$$[x, p] = -i\hbar, \quad \Rightarrow \quad \Delta x \Delta p \geq \hbar$$

From

$$p^2 c^2 + m^2 c^4 = E^2$$

get

$$\Delta E = \frac{p \Delta p}{E} c^2 \geq \frac{p \hbar c^2}{E \Delta x} \quad \text{or} \quad \Delta x \geq \frac{pc}{E} \left( \frac{\hbar c}{\Delta E} \right)$$

To avoid new particle creation we require  $\Delta E \leq mc^2$ . Then we get a lower bound on  $\Delta x$

$$\Delta x \geq \frac{pc}{E} \frac{\hbar}{mc} = \left( \frac{v}{c} \right) \left( \frac{\hbar}{mc} \right)$$

For relativistic particle  $\frac{v}{c} \approx 1$ , then

$$\Delta x \geq \left( \frac{h}{mc} \right) \quad \text{Compton wavelength}$$

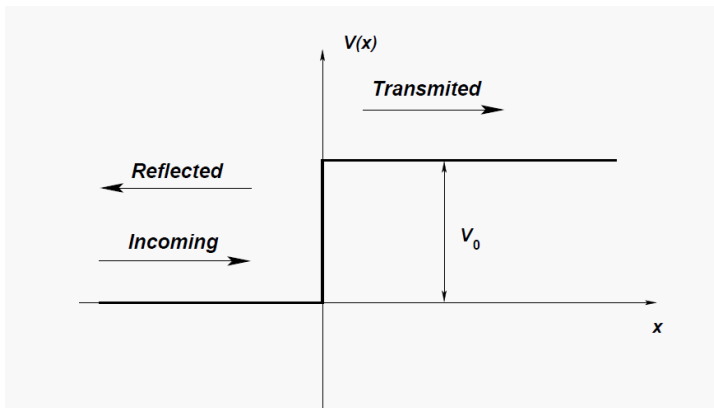
⇒ Particle can not be confined to a interval smaller than its Compton wavelength

## Klein paradox

To illustrate this feature we will study Klein's paradox in the context of the Klein-Gordon equation given by

$$\left( \frac{\partial^2}{\partial t^2} - \nabla^2 - m^2 \right) \psi(x, t) = 0$$

- Let us consider a square potential with height  $V_0 > 0$  as shown in the figure,



A solution to the wave equation in regions I and II is given by

$$\psi_I(x, t) = e^{-iEt - ip_1x} + R e^{-iEt + ip_1x}$$

$$\psi_{II}(x, t) = T e^{-iEt - ip_2x}$$

where

$$p_1 = \sqrt{E^2 - m^2}, \quad p_2 = \sqrt{(E - V_0)^2 - m^2}$$

The constants  $R$  and  $T$  are computed by matching the two solutions across the boundary  $x = 0$ . The conditions  $\psi_I(t, 0) = \psi_{II}(t, 0)$  and  $\partial_x \psi_I(t, 0) = \partial_x \psi_{II}(t, 0)$  give

$$1 + R = T, \quad (1 - R)p_1 = Tp_2$$

Solve for  $R$  and  $T$

$$T = \frac{2p_1}{p_1 + p_2}, \quad R = \frac{p_1 - p_2}{p_1 + p_2}$$

- if  $E - m > V_0$  both  $p_1$  and  $p_2$  are real and there are both transmitted and reflected wave.
- If  $E - m < V_0$  and  $E - m < V_0 - 2m$ , then  $p_2$  is imaginary, we get a reflected wave, transmitted wave being exponentially damped within a distance of a Compton wavelength inside the barrier and there is total reflection.
- when  $V_0 > 2m$  and  $V_0 - 2m < E - m < V_0$  then both  $p_1$  and  $p_2$  are real and there are both reflected and transmitted waves. This implies that there is a nonvanishing probability of finding the particle at any point across the barrier with negative kinetic energy ( $E - m - V_0 < 0$ )!

This weird result is known as **Klein's paradox**. This result can only be understood in terms of particle creation at sudden potential step.

## Gauge Theory—Quantum Field Theory with Local Symmetry

### **Gauge principle**

All fundamental Interactions are described in terms of gauge theories;

- 1 Strong Interaction-QCD;  
gauge theory based on  $SU(3)$  symmetry
- 2 Electromagnetic and Weak interaction-  
gauge theory based on  $SU(2) \times U(1)$  symmetry
- 3 Gravitational interaction-  
Einstein's theory-gauge theory of local coordinate transformation.

## Natural unit

$$\hbar = c = 1$$

In MKS units

$$\hbar = 1.055 \times 10^{-34} \text{ J sec}, \quad c = 2.99 \times 10^8 \text{ m/sec}$$

In this unit, at the end of the calculation one puts back factors of  $\hbar$  and  $c$  depending on the physical quantities in the problem.

For example, the quantity  $m_e$  can have following different meanings depending on the contexts;

① Reciprocal length

$$m_e = \frac{1}{\frac{\hbar}{m_e c}} = \frac{1}{3.86 \times 10^{-11} \text{ cm}}$$

② Reciprocal time

$$m_e = \frac{1}{\frac{\hbar}{m_e c^2}} = \frac{1}{1.29 \times 10^{-21} \text{ sec}}$$

③ Energy

$$m_e = m_e c^2 = 0.511 \text{ Mev}$$

④ Momentum

$$m_e = m_e c = 0.511 \text{ Mev}/c$$

The following conversion relations

$$\hbar = 6.58 \times 10^{-22} \text{ Mev} - \text{sec} \quad \hbar c = 1.973 \times 10^{-11} \text{ Mev} - \text{cm}$$

are quite useful in getting the physical quantities in the right units.

Example: Thomson cross section

$$\sigma = \frac{8\pi\alpha^2}{3m_e^2} = \frac{8\pi\alpha^2(\hbar c)^2}{3m_e^2 c^4} = \left(\frac{1}{137}\right)^2 \times \frac{(1.973 \times 10^{-11} \text{ Mev} - \text{cm})^2}{(0.5 \text{ Mev})^2} \times \left(\frac{8\pi}{3}\right) \simeq 6.95 \times 10^{-25} \text{ cm}^2$$

Useful conversion factor

$$1 \text{ ev} = 1.6 \times 10^{-19} \text{ J}, \quad 1 \text{ Gev} = 1.6 \times 10^{-10} \text{ J} \quad \text{or} \quad 1 \text{ J} = \frac{1}{1.6} \times 10^{10} \text{ Gev}$$



# Review of Special Relativity

Basic principles of special relativity :

- 1 The speed of light : same in all inertial frames.
- 2 Physical laws: same forms in all inertial frames.

Lorentz transformation—relate coordinates in different inertial frame

$$x' = \frac{x - vt}{\sqrt{1 - v^2}} \quad y' = y, \quad z' = z, \quad t' = \frac{t - vx}{\sqrt{1 - v^2}}$$

⇒

$$t^2 - x^2 - y^2 - z^2 = t'^2 - x'^2 - y'^2 - z'^2$$

Proper time  $\tau^2 = t^2 - \vec{r}^2$  invariant under Lorentz transformation.

Particle moves from  $\vec{r}_1(t_1)$  to  $\vec{r}_2(t_2)$ . The speed is

$$|\vec{v}| = \frac{1}{|t_2 - t_1|} \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2}$$

For  $|\vec{v}| = 1$ ,

$$(t_1 - t_2)^2 = |\vec{r}_1 - \vec{r}_2|^2$$

this is invariant under Lorentz transformation ⇒ speed of light same in all inertial frames.

Another form of the Lorentz transformation

$$x' = \cosh \omega x - \sinh \omega t, \quad y' = y, \quad z' = z, \quad t' = \sinh \omega x - \cosh \omega t$$

where

$$\tanh \omega = v$$

For infinitesimal interval  $(dt, dx, dy, dz)$ , proper time is

$$(d\tau)^2 = (dt)^2 - (dx)^2 - (dy)^2 - (dz)^2$$

**Minkowski space,**

$$x^\mu = (t, x, y, z) = (x^0, x^1, x^2, x^3), \quad 4\text{-vector}$$

Lorentz invariant product can be written as

$$x^2 = (x_0)^2 - (x_1)^2 - (x_2)^2 - (x_3)^2 = x^\mu x^\nu g_{\mu\nu}$$

where

$$g_{\mu\nu} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

Define another 4-vector

$$x_\mu = g_{\mu\nu} x^\nu = (t, -x^1, -x^2, -x^3) = (t, -\vec{r})$$

so that

$$x^2 = x^\mu x_\mu$$

For infinitesimal coordinates

$$(dx)^2 = (dx^\mu)(dx_\mu) = dx^\mu dx^\nu g_{\mu\nu} = (dx^0)^2 - (d\vec{x})^2$$

Write the Lorentz transformation as

$$x^\mu \rightarrow x'^\mu = \Lambda_\nu^\mu x^\nu$$

For example for Lorentz transformation in the  $x$ -direction, we have

$$\Lambda_\nu^\mu = \begin{pmatrix} \frac{1}{\sqrt{1-\beta^2}} & \frac{-\beta}{\sqrt{1-\beta^2}} & 0 & 0 \\ \frac{-\beta}{\sqrt{1-\beta^2}} & \frac{1}{\sqrt{1-\beta^2}} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Write

$$x'^2 = x'^\mu x'^\nu g_{\mu\nu} = \Lambda_\alpha^\mu \Lambda_\beta^\nu g_{\mu\nu} x^\alpha x^\beta$$

then  $x^2 = x'^2$  implies

$$\Lambda_\alpha^\mu \Lambda_\beta^\nu g_{\mu\nu} = g_{\alpha\beta}$$

and is called **pseudo-orthogonality** relation.

# Energy and Momentum

Start from

$$dx^\mu = (dx^0, dx^1, dx^2, dx^3)$$

Proper time is Lorentz invariant and has the form,

$$(d\tau)^2 = dx^\mu dx_\mu = (dt)^2 - \left(\frac{d\vec{x}}{dt}\right)^2 (dt)^2 = (1 - \vec{v}^2)(dt)^2$$

4 – velocity,

$$u^\mu = \frac{dx^\mu}{d\tau} = \left(\frac{dx^0}{d\tau}, \frac{d\vec{x}}{d\tau}\right)$$

there is a constraint

$$u^\mu u_\mu = \frac{dx^\mu}{d\tau} \frac{dx_\mu}{d\tau} = 1$$

Note that

$$\vec{u} = \frac{d\vec{x}}{d\tau} = \frac{d\vec{x}}{dt} \left(\frac{dt}{d\tau}\right) = \frac{1}{\sqrt{1-v^2}} \vec{v} \approx \vec{v}, \quad \text{for } v \ll 1$$

4 – velocity  $\implies$  4 – momentum

$$p^\mu = mu^\mu = \left(\frac{m}{\sqrt{1-v^2}}, \frac{m\vec{v}}{\sqrt{1-v^2}}\right)$$

For  $v \ll 1$ ,

$$p^0 = \frac{m}{\sqrt{1-v^2}} = m\left(1 + \frac{1}{2}v^2 + \dots\right) = m + \frac{m}{2}v^2 + \dots, \quad \text{energy}$$

$$\vec{p} = m\vec{v} \frac{1}{\sqrt{1-v^2}} = m\vec{v} + \dots \quad \text{momentum}$$

$$p^\mu = (E, \vec{p})$$

Note that

$$p^2 = E^2 - \vec{p}^2 = \frac{m^2}{1-v^2} [1-v^2] = m^2$$

# Tensor analysis

Physical laws take the same forms in all inertial frames, if we write them in terms of tensors in Minkowski space.

Basically, tensors are

tensors  $\sim$  product of vectors

2 different types of vectors,

$$x'^{\mu} = \Lambda^{\mu}_{\nu} x^{\nu}, \quad x'_{\mu} = \Lambda_{\mu}^{\nu} x_{\nu}$$

multiply these vectors to get 2nd rank tensors,

$$T'^{\mu\nu} = \Lambda^{\mu}_{\alpha} \Lambda^{\nu}_{\beta} T^{\alpha\beta}, \quad T'_{\mu\nu} = \Lambda_{\mu}^{\alpha} \Lambda_{\nu}^{\beta} T_{\alpha\beta}, \quad T'^{\mu}_{\nu} = \Lambda^{\mu}_{\alpha} \Lambda_{\nu}^{\beta} T^{\alpha}_{\beta}$$

In general,

$$T'^{\mu_1 \dots \mu_n}_{\nu_1 \dots \nu_m} = \Lambda^{\mu_1}_{\alpha_1} \dots \Lambda^{\mu_n}_{\alpha_n} \Lambda_{\nu_1}^{\beta_1} \dots \Lambda_{\nu_m}^{\beta_m} T^{\alpha_1 \dots \alpha_n}_{\beta_1 \dots \beta_m}$$

transformation of tensor components is linear and homogeneous.

**Tensor operations**; operation which preserves the tensor property

- 1 Multiplication by a constant,  $(cT)$  has the same tensor properties as  $T$
- 2 Addition of tensor of same rank
- 3 Multiplication of two tensors
- 4 Contraction of tensor indices. For example,  $T_{\mu}^{\mu\alpha\beta\gamma}$  is a tensor of rank 3 while  $T_{\nu}^{\mu\alpha\beta\gamma}$  is a tensor of rank 5. This follows from the pseudo-orthogonality relation
- 5 Symmetrization or anti-symmetrization of indices. This can be seen as follows. Suppose  $T^{\mu\nu}$  is a second rank tensor,

$$T'^{\mu\nu} = \Lambda_{\alpha}^{\mu} \Lambda_{\beta}^{\nu} T^{\alpha\beta}$$

interchanging the indices

$$T'^{\nu\mu} = \Lambda_{\alpha}^{\nu} \Lambda_{\beta}^{\mu} T^{\alpha\beta} = \Lambda_{\beta}^{\nu} \Lambda_{\alpha}^{\mu} T^{\beta\alpha}$$

Then

$$T'^{\mu\nu} + T'^{\nu\mu} = \Lambda_{\alpha}^{\mu} \Lambda_{\beta}^{\nu} (T^{\alpha\beta} + T^{\beta\alpha})$$

symmetric tensor transforms into symmetric tensor. Similarly, the anti-symmetric tensor transforms into antisymmetric one.

- 6  $g_{\mu\nu}$ , and  $\varepsilon^{\alpha\beta\gamma\delta}$  have the property

$$\Lambda_{\alpha}^{\mu} \Lambda_{\beta}^{\nu} g_{\mu\nu} = g_{\alpha\beta}, \quad \varepsilon^{\alpha\beta\gamma\delta} \det(\Lambda) = \Lambda_{\mu}^{\alpha} \Lambda_{\nu}^{\beta} \Lambda_{\rho}^{\gamma} \Lambda_{\sigma}^{\delta} \varepsilon^{\mu\nu\rho\sigma}$$

$g_{\mu\nu}$ , and  $\varepsilon^{\alpha\beta\gamma\delta}$  transform in the same way as tensors if  $\det(\Lambda) = 1$ .

Example:  $M^{\mu\nu} = x^{\mu} p^{\nu} - x^{\nu} p^{\mu}$ ,  $F^{\mu\nu} = \partial^{\mu} A^{\nu} - \partial^{\nu} A^{\mu}$  2nd\_rank antisymmetric tensor.



Note that if all components of a tensor vanish in one inertial frame they vanish in all inertial frame. Suppose

$$f^\mu = ma^\mu$$

Define

$$t^\mu = f^\mu - ma^\mu$$

then  $t^\mu = 0$  in this inertial frame. In another inertial frame,

$$t'^\mu = f'^\mu - ma'^\mu = 0$$

we get

$$f'^\mu = ma'^\mu$$

Thus physical laws in tensor form are same in all inertial frames .

**Action principle:** actual trajectory of a particle minimizes the action

Particle mechanics

A particle moves from  $x_1$  at  $t_1$  to  $x_2$  at  $t_2$ . Write the action as

$$S = \int_{t_1}^{t_2} L(x, \dot{x}) dt \quad L : \text{Lagrangian}$$

For the least action, make a small change  $x(t)$ ,

$$x(t) \rightarrow x'(t) = x(t) + \delta x(t)$$

with end points fixed

$$i.e. \quad \delta x(t_1) = \delta x(t_2) = 0 \quad \text{initial conditions}$$

Then

$$\delta S = \int_{t_1}^{t_2} \left[ \frac{\partial L}{\partial x} \delta x + \frac{\partial L}{\partial \dot{x}} \delta(\dot{x}) \right] dt$$

Note that

$$\delta \dot{x} = \dot{x}'(t) - \dot{x}(t) = \frac{d}{dt} [\delta(x)]$$

Integrate by parts and used the initial conditions

$$\delta S = \int_{t_1}^{t_2} \left[ \frac{\partial L}{\partial x} \delta x + \frac{\partial L}{\partial \dot{x}} \frac{d}{dt} (\delta x) \right] dt = \int_{t_1}^{t_2} \left[ \frac{\partial L}{\partial x} - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{x}} \right) \right] \delta x dt$$

Since  $\delta x(t)$  is arbitrary,  $\delta S = 0$  implies

$$\frac{\partial L}{\partial x} - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{x}} \right) = 0 \quad \text{Euler-Lagrange equation}$$

Conjugate momentum is

$$p \equiv \frac{\partial L}{\partial \dot{x}}$$

Hamiltonian is ,

$$H(p, q) = p\dot{x} - L(x, \dot{x})$$

Consider the simple case

$$m \frac{d^2 x}{dt^2} = - \frac{\partial V}{\partial x}$$

Suppose

$$L = \frac{m}{2} \left( \frac{dx}{dt} \right)^2 - V(x)$$

then

$$\frac{\partial L}{\partial x} = \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{x}} \right), \quad \Rightarrow \quad - \frac{\partial V}{\partial x} = m \frac{d^2 x}{dt^2}$$

Hamiltonian

$$H = p\dot{x} - L = \frac{m}{2} (\dot{x})^2 + V(x) \quad \text{where} \quad p = \frac{\partial L}{\partial \dot{x}} = m\dot{x}$$

is just the total energy.

## Generalization

$$x(t) \rightarrow q_i(t), \quad i = 1, 2, \dots, n$$

$$S = \int_{t_1}^{t_2} L(q_i, \dot{q}_i) dt$$

## Euler-Lagrange equations

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}_i} \right) - \frac{\partial L}{\partial q_i} = 0 \quad i = 1, 2, \dots, n$$

$$p_i = \frac{\partial L}{\partial \dot{q}_i}, \quad H = \sum_i p_i \dot{q}_i - L$$

**Example:** harmonic oscillator in 3-dimensions

Lagrangian

$$L = T - V = \frac{m}{2} (\dot{x}_1^2 + \dot{x}_2^2 + \dot{x}_3^2) - \frac{m\omega^2}{2} (x_1^2 + x_2^2 + x_3^2)$$

and

$$\frac{\partial L}{\partial x_i} = -m\omega^2 x_i, \quad \frac{\partial L}{\partial \dot{x}_i} = m\dot{x}_i$$

Euler-Lagrange equation

$$m\ddot{x}_i = -m\omega^2 x_i$$

same as Newton's second law.

**Remarks:**

- We need action principle for quantization
- In action principle formulation, the discussion of symmetry is simpler
- Can take into account the constraints in the coordinates in terms of Lagrange multipliers

## Field Theory

Field theory  $\sim$  limiting case where number of degrees of freedom is infinite.  $q_i(t) \rightarrow \phi(\vec{x}, t)$ .

Action

$$S = \int L(\phi, \partial_\mu \phi) d^3x dt \quad L : \text{Lagrangian density}$$

Variation of action

$$\delta S = \int \left[ \frac{\partial L}{\partial \phi} \delta \phi + \frac{\partial L}{\partial (\partial_\mu \phi)} \delta (\partial_\mu \phi) \right] dx^4 = \int \left[ \frac{\partial L}{\partial \phi} - \partial_\mu \frac{\partial L}{\partial (\partial_\mu \phi)} \right] \delta \phi dx^4$$

Use  $\delta(\partial_\mu \phi) = \partial_\mu(\delta \phi)$  and do the integration by part. then  $\delta S = 0$  implies

$$\implies \frac{\partial L}{\partial \phi} = \partial_\mu \left( \frac{\partial L}{\partial (\partial_\mu \phi)} \right) \quad \text{Euler-Lagrange equation}$$

Conjugate momentum density

$$\pi(\vec{x}, t) = \frac{\partial L}{\partial (\partial_0 \phi)}$$

and Hamiltonian density

$$H = \pi \dot{\phi} - L$$

Generalization to more than one field

$$\phi(\vec{x}, t) \rightarrow \phi_i(\vec{x}, t), \quad i = 1, 2, \dots, n$$

Equations of motion are

$$\frac{\partial L}{\partial \phi_i} = \partial_\mu \left( \frac{\partial L}{\partial (\partial_\mu \phi_i)} \right) \quad i = 1, 2, \dots, n$$

and conjugate momentum

$$\pi_i(\vec{x}, t) = \frac{\partial L}{\partial (\partial_0 \phi_i)}$$

Hamiltonian density is

$$H = \sum_i \pi_i \dot{\phi}_i - L$$

## Symmetry and Noether's Theorem

Continuous symmetry  $\implies$  conservation law, e.g. invariance under time translation

$$t \rightarrow t + a, \quad a \text{ is arbitrary constant}$$

gives energy conservation. Newton's equation for a force derived from a potential  $V(\vec{x}, t)$  is,

$$m \frac{d^2 \vec{x}}{dt^2} = -\vec{\nabla} V(\vec{x}, t)$$

Suppose  $V(\vec{x}, t) = V(\vec{x})$ , then invariant under time translation and

$$m \frac{d\vec{x}}{dt} \cdot \left( \frac{d^2 \vec{x}}{dt^2} \right) = - \left( \frac{d\vec{x}}{dt} \right) \cdot \vec{\nabla} V = - \frac{d}{dt} [V(\vec{x})]$$

Or

$$\frac{d}{dt} \left[ \frac{1}{2} m \left( \frac{d\vec{x}}{dt} \right)^2 + V(\vec{x}) \right] = 0, \quad \text{energy conservation}$$

Similarity, invariance under spatial translation

$$\vec{x} \rightarrow \vec{x} + \vec{a}$$

gives momentum conservation and invariance under rotations gives angular momentum conservation. Noether's theorem : unified treatment of symmetries in the Lagrangian formalism.

**Particle mechanics**

Action in classical mech

$$S = \int L(q_i, \dot{q}_i) dt$$

Suppose  $S$  is invariant under a continuous symmetry transformation,

$$q_i \rightarrow q'_i = f_i(q_j),$$

For infinitesimal change

$$q_i \rightarrow q'_i \simeq q_i + \delta q_i$$

The change of  $S$

$$\delta S = \int \left[ \frac{\partial L}{\partial q_i} \delta q_i + \frac{\partial L}{\partial \dot{q}_i} \delta \dot{q}_i \right] dt \quad \text{where} \quad \delta \dot{q}_i \rightarrow \frac{d}{dt}(\delta q_i)$$

Using the equation of motion,

$$\frac{\partial L}{\partial q_i} = \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}_i} \right)$$

we can write  $\delta S$  as

$$\delta S = \int \left[ \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}_i} \right) \delta q_i + \frac{\partial L}{\partial \dot{q}_i} \frac{d}{dt}(\delta q_i) \right] dt = \int \left[ \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}_i} \delta q_i \right) \right] dt$$

Thus  $\delta S = 0 \Rightarrow$

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}_i} \delta q_i \right) = 0$$



This can be written as

$$\text{or } \frac{dA}{dt} = 0, \quad A = \frac{\partial L}{\partial \dot{q}_i} \delta q_j$$

$A$  is the conserved charge.

Note if  $\delta L \neq 0$  but changes by a total time derivative  $\delta L = \frac{d}{dt} K$ , we still get the conservation law in the form,

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}_i} \delta q_i - K \right) = 0$$

because the action is still invariant. For example, for translation in time,  $t \longrightarrow t + \varepsilon$ ,

$$q(t + \varepsilon) = q(t) + \varepsilon \frac{dq}{dt}, \quad \implies \delta q = \varepsilon \frac{dq}{dt}$$

Similarly,

$$\delta L = \frac{dL}{dt}$$

The conservation law is then

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}_i} \delta q_i - L \right) = 0$$

Or

$$\frac{dH}{dt} = 0, \quad \text{with} \quad H = \frac{\partial L}{\partial \dot{q}_i} \dot{q}_i - L$$

**Example:** rotational symmetry in 3-dimension  
action

$$S = \int L(x_i, \dot{x}_i) dt$$

Suppose  $S$  is invariant under rotation,

$$x_i \rightarrow x'_i = R_{ij}x_j, \quad RR^T = R^T R = 1 \quad \text{or} \quad R_{ij}R_{ik} = \delta_{jk}$$

For infinitesimal rotations

$$R_{ij} = \delta_{ij} + \varepsilon_{ij} \quad |\varepsilon_{ij}| \ll 1$$

Orthogonality requires,

$$(\delta_{ij} + \varepsilon_{ij})(\delta_{ik} + \varepsilon_{ik}) = \delta_{jk} \implies \varepsilon_{jk} + \varepsilon_{kj} = 0 \quad \text{i, e,} \quad \varepsilon_{jk} \quad \text{is antisymmetric}$$

$$\delta x_i = \varepsilon_{ij} x_j$$

We can compute the conserved charges as

$$J = \frac{\partial L}{\partial \dot{x}} \varepsilon_{ij} x_j = \varepsilon_{ij} p_i x_j$$

If we write  $\varepsilon_{ij} = -\varepsilon_{ijk} \theta_k$

$$J = -\theta_k \varepsilon_{ijk} p_i x_j = -\theta_k J_k \quad J_k = \varepsilon_{ijk} x_i p_j$$

$J_k$  k-th component of angular momentum.

## Field Theory

Start from the action

$$S = \int L(\phi, \partial_\mu \phi) d^4x$$

Symmetry transformation,

$$\phi(x) \rightarrow \phi'(x'),$$

which includes the change of coordinates,

$$x^\mu \rightarrow x'^\mu \neq x^\mu$$

Infinitesimal transformation

$$\delta\phi = \phi'(x') - \phi(x), \quad \delta x'^\mu = x'^\mu - x^\mu$$

need to include the change in the volume element

$$d^4x' = J d^4x \quad \text{where} \quad J = \left| \frac{\partial(x'_0, x'_1, x'_2, x'_3)}{\partial(x_0, x_1, x_2, x_3)} \right|$$

$J$ : Jacobian for the coordinate transformation. For infinitesimal transformation,

$$J = \left| \frac{\partial x'^\mu}{\partial x^\nu} \right| \approx |g_\nu^\mu + \frac{\partial(\delta x^\mu)}{\partial x^\nu}| \approx 1 + \partial_\mu(\delta x^\mu)$$

we have used the relation

$$\det(\mathbf{1} + \varepsilon) \approx \mathbf{1} + \text{Tr}(\varepsilon) \quad \text{for } |\varepsilon| \ll 1$$

Then

$$d^4x' = d^4x(1 + \partial_\mu(\delta x^\mu))$$

change in the action is

$$\delta S = \int \left[ \frac{\partial L}{\partial \phi} \delta \phi + \frac{\partial L}{\partial (\partial_\mu \phi)} \delta (\partial_\mu \phi) + L \partial_\mu (\delta x^\mu) \right] dx^4$$

Define the change of  $\phi$  for fixed  $x^\mu$ ,

$$\bar{\delta} \phi(x) = \phi'(x) - \phi(x) = \phi'(x) - \phi'(x') + \phi'(x') - \phi(x) = -\partial^\mu \phi' \delta x_\mu + \delta \phi$$

$$\text{or } \delta \phi = \bar{\delta} \phi + (\partial_\mu \phi) \delta x^\mu$$

Similarly,

$$\delta (\partial_\mu \phi) = \bar{\delta} (\partial_\mu \phi) + \partial_\nu (\partial_\mu \phi) \delta x^\nu$$

Operator  $\bar{\delta}$  commutes with the derivative operator  $\partial_\mu$ ,

$$\bar{\delta} (\partial_\mu \phi) = \partial_\mu (\bar{\delta} \phi)$$

Then

$$\delta S = \int \left[ \frac{\partial L}{\partial \phi} (\bar{\delta} \phi + (\partial_\mu \phi) \delta x^\mu) + \frac{\partial L}{\partial (\partial_\mu \phi)} (\bar{\delta} (\partial_\mu \phi) + \partial_\nu (\partial_\mu \phi) \delta x^\nu) + L \partial_\mu (\delta x^\mu) \right] dx^4$$

Use equation of motion

$$\frac{\partial L}{\partial \phi} = \partial^\mu \left( \frac{\partial L}{\partial (\partial_\mu \phi)} \right)$$

we get

$$\frac{\partial L}{\partial \phi} \bar{\delta} \phi + \frac{\partial L}{\partial (\partial_\mu \phi)} \bar{\delta} (\partial_\mu \phi) = \partial^\mu \left( \frac{\partial L}{\partial (\partial_\mu \phi)} \bar{\delta} \phi + \frac{\partial L}{\partial (\partial_\mu \phi)} \partial_\mu (\bar{\delta} \phi) \right) = \partial^\mu \left[ \frac{\partial L}{\partial (\partial_\mu \phi)} \bar{\delta} \phi \right]$$

Combine other terms as

$$\begin{aligned} \left[ \frac{\partial L}{\partial \phi} (\partial_\nu \phi) + \frac{\partial L}{\partial (\partial_\mu \phi)} \partial_\nu (\partial_\mu \phi) \right] \delta x^\nu + L \partial_\nu (\delta x^\nu) &= (\partial_\nu L) \delta x^\nu + L \partial_\nu (\delta x^\nu) \\ &= \partial_\nu (L \delta x^\nu) \end{aligned}$$

Then

$$\delta S = \int dx^4 \partial_\mu \left[ \frac{\partial L}{\partial (\partial_\mu \phi)} \bar{\delta} \phi + L \delta x^\mu \right]$$

and if  $\delta S=0$  under the symmetry transformation, then

$$\partial^\mu J_\mu = \partial^\mu \left[ \frac{\partial L}{\partial(\partial_\mu \phi)} \bar{\delta} \phi + L \delta x^\mu \right] = 0 \quad \text{current conservation}$$

Simple case: space-time translation

Here the coordinate transformation is,

$$x^\mu \rightarrow x'^\mu = x^\mu + a^\mu \implies \phi'(x + a) = \phi(x)$$

then

$$\bar{\delta} \phi = -a^\mu \partial_\mu \phi$$

and the conservation laws take the form

$$\partial^\mu \left[ \frac{\partial L}{\partial(\partial_\mu \phi)} (-a^\nu \partial_\nu \phi) + L a^\mu \right] = -\partial^\mu (T_{\mu\nu} a^\nu) = 0$$

where

$$T_{\mu\nu} = \frac{\partial L}{\partial(\partial_\mu \phi)} \partial_\nu \phi - g_{\mu\nu} L \quad \text{energy momentum tensor}$$

In particular,

$$T_{0i} = \frac{\partial L}{\partial(\partial_0 \phi)} \partial_i \phi$$

and

$$P_i = \int dx^3 T_{0i} \quad \text{momentum of the fields}$$